**IN THE SPECIFICATION**:

Please amend paragraph [0020] as follows:

**[0020]** On the one hand, the control and analyzing device 18 forwards the information transmitted by the cameras 16 and 14 directly to the driver. It also carries out a differential contrast evaluation. As a result, the ~~extinctions of the atmosphere~~ atmospheric absorbance can be determined in the two spectral regions. If a visual range model is also stored in the control and analyzing device 18, by way of the ~~determined extinctions~~ detected absorbances and by means of a differential contrast evaluation, a conclusion can also be drawn with respect to the driver's visual range.

Please amend paragraph [0021] as follows:

**[0021]** This visual range and/or these ~~extinctions~~ detected absorbances can then be utilized for adapting control parameters or for recommending a vehicle speed to the driver.

Please amend paragraph [0022] as follows:

**[0022]** However, for determining the ~~extinction~~ atmospheric absorbance in the visible spectral region, another system, such as a ~~LIDAR~~ light detection and ranging (LIDAR) system may also be used.

Please add new paragraph [0023] as follows:

**[0023]** A memory device 22 can be provided in which a visual range model is stored. A device 24 is provided by which a conclusion can be drawn with respect to the visual range from information of the analyzing device18.